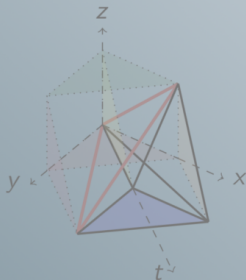
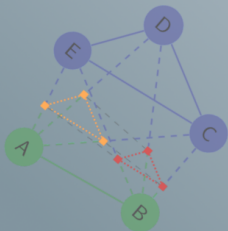


Discontinuous Galerkin Space-Time Finite Element
method for two-phase mass transport

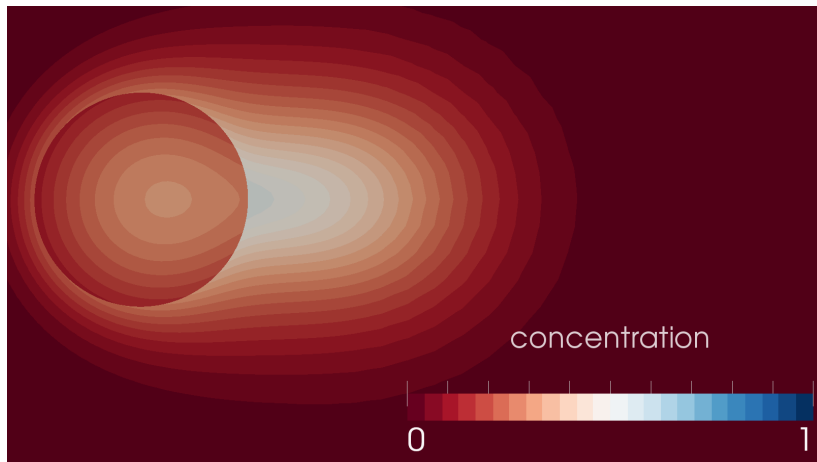
Christoph Lehrenfeld, Arnold Reusken

LNM, RWTH Aachen

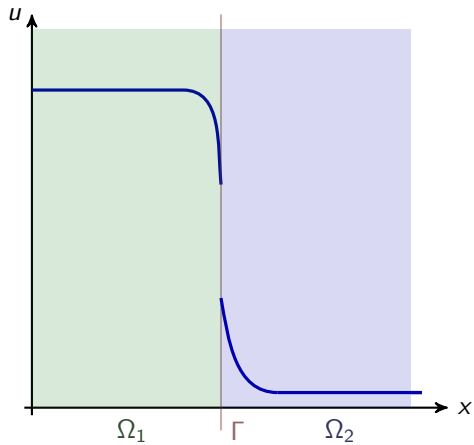
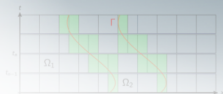
Luxembourg, September 2012

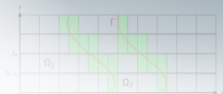


Two-phase mass transport: A movie

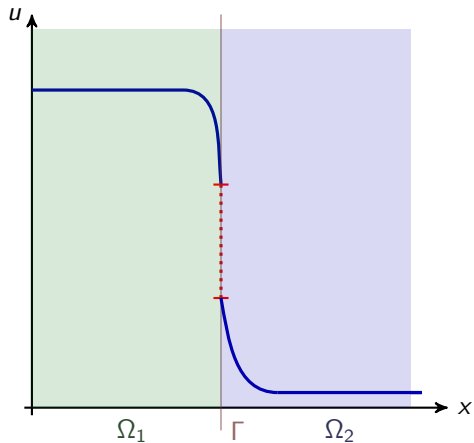


Situation at the interface



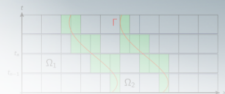


Situation at the interface

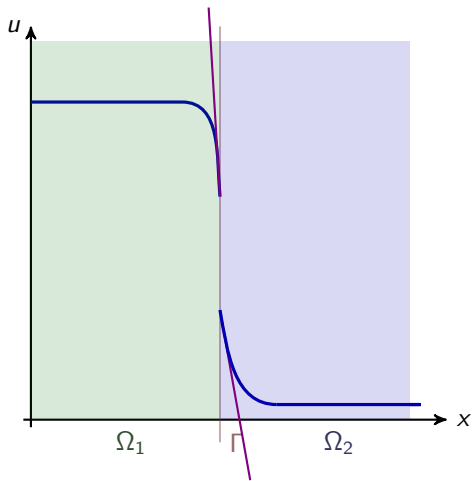


discontinuous conc.

$$u_1/u_2 = \beta_2/\beta_1$$



Situation at the interface

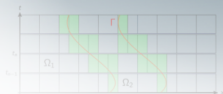


discontinuous conc.

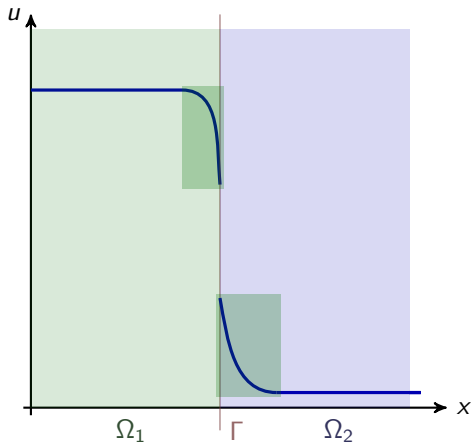
$$u_1/u_2 = \beta_2/\beta_1$$

disc. normal derivative

$$\alpha_1 \frac{\partial u_1}{\partial \mathbf{n}_1} = \alpha_2 \frac{\partial u_2}{\partial \mathbf{n}_2}$$



Situation at the interface



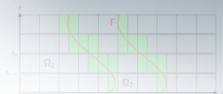
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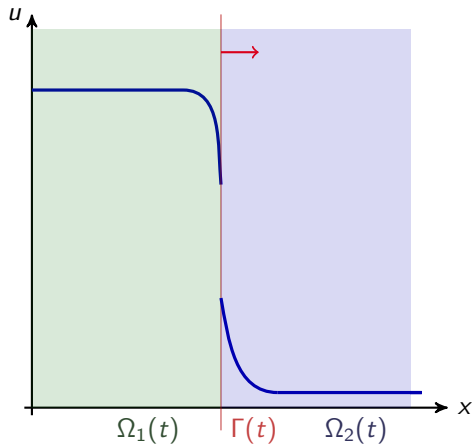
disc. normal derivative

$$\alpha_1 \frac{\partial u_1}{\partial \mathbf{n}_1} = \alpha_2 \frac{\partial u_2}{\partial \mathbf{n}_2}$$

sharp layers



Situation at the interface



discontinuous conc.

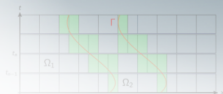
$$u_1/u_2 = \beta_2/\beta_1$$

disc. normal derivative

$$\alpha_1 \frac{\partial u_1}{\partial \mathbf{n}_1} = \alpha_2 \frac{\partial u_2}{\partial \mathbf{n}_2}$$

sharp layers

moving interface $\Gamma(t)$



Mass transport

Mass transport equation

$$\frac{\partial u}{\partial t} + \mathbf{w} \cdot \nabla u - \alpha \Delta u = 0 \quad \text{in } \Omega_1 \cup \Omega_2,$$

$$[-\alpha \nabla u] \cdot \mathbf{n} = 0 \quad \text{on } \Gamma,$$

$$[[\beta u]] = 0 \quad \text{on } \Gamma.$$

$$\mathcal{V} \cdot \mathbf{n} = \mathbf{w} \cdot \mathbf{n} \quad \text{on } \Gamma.$$

$$\operatorname{div}(\mathbf{w}) = 0 \quad \text{in } \Omega$$

u : concentration,

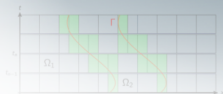
α : piecewise constant diffusion coefficients,

β : piecewise constant Henry coefficients,

\mathbf{w} : convection velocity (from Navier Stokes)

\mathcal{V} : the interface velocity

Henry condition: **discontinuity** in u .



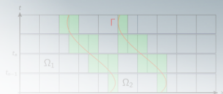
Numerical Aspects

Mass transport equation

$$\frac{\partial u}{\partial t} + \mathbf{w} \cdot \nabla u - \alpha \Delta u = 0 \quad \text{in } \Omega_1(t) \cup \Omega_2(t),$$

$$\llbracket -\alpha \nabla u \rrbracket \cdot \mathbf{n} = 0 \quad \text{on } \Gamma(t),$$

$$\llbracket \beta u \rrbracket = 0 \quad \text{on } \Gamma(t).$$



Numerical Aspects

Mass transport equation

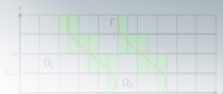
$$\frac{\partial u}{\partial t} + \mathbf{w} \cdot \nabla u - \alpha \Delta u = 0 \quad \text{in } \Omega_1(t) \cup \Omega_2(t),$$

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$$[[\beta u]] = 0 \quad \text{on } \Gamma(t).$$

Numerical Challenges

- ▶ Level set to capture the interface
 \Rightarrow Interface is not aligned with the mesh (might depend on time)
- ▶ concentration has discontinuities (approximation)
- ▶ time integration for (non-matched) moving interfaces
- ▶ problem is typically highly convection dominated (stability)



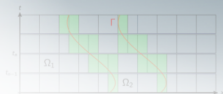
Numerical Aspects

Numerical Challenges

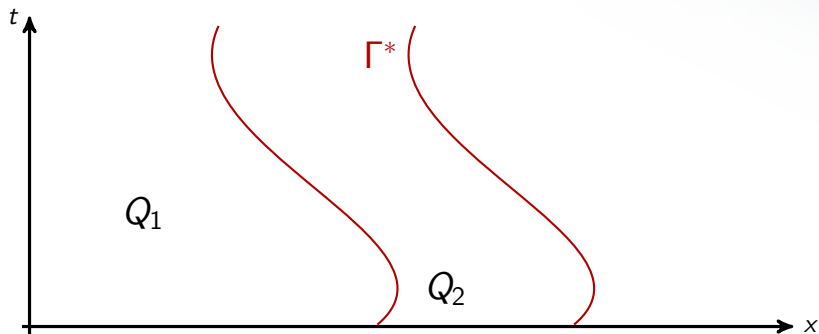
- ▶ Level set to capture the interface
⇒ Interface is not aligned with the mesh (might depend on time)
- ▶ concentration has discontinuities (approximation)
- ▶ time integration for (non-matched) moving interfaces
- ▶ problem is typically highly convection dominated (stability)

Numerical Approaches

- ▶ Space-time formulation on each time slab
- ▶ Extended Finite Element space (XFEM)
- ▶ Nitsche-type technique to enforce Henry's law in a weak sense
- ▶ (Space-time Streamline Diffusion) Stabilization



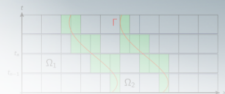
Space-time weak formulation I



Anisotropic Spaces; $Q = Q_1 \cup Q_2$

$$V_\beta = \{ u \in L^2(Q) \mid u_i \in H^{1,0}(Q_i), i = 1, 2, u|_{\partial\Omega} = 0, \llbracket \beta u \rrbracket_{\Gamma_*} = 0 \}$$

$$W_\beta = \{ v \in V_\beta \mid \frac{\partial v}{\partial t} \in H_0^{1,0}(Q)' \}.$$



Space-time weak formulation II

Well-posed weak formulation [Gross/Reusken 11]

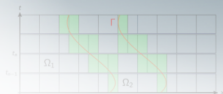
Determine $u \in W_\beta$ with $u(\cdot, 0) = 0$ such that

$$\frac{\partial u}{\partial t}(v) - \int_Q u \mathbf{w} \cdot \nabla v \, dx \, dt + \sum_{i=1}^2 \int_{Q_i} \alpha_i \nabla u_i \cdot \nabla v \, dx \, dt = \int_Q f v \, dx \, dt$$

for all $v \in H_0^{1,0}(Q) \neq V_\beta$

Remarks:

- ▶ Space-time ($n+1$ dimensional) formulation
- ▶ Trial functions are discontinuous across Γ_*
- ▶ Condition $[[\beta u]]_\Gamma = 0$ **essential** condition in space W_β



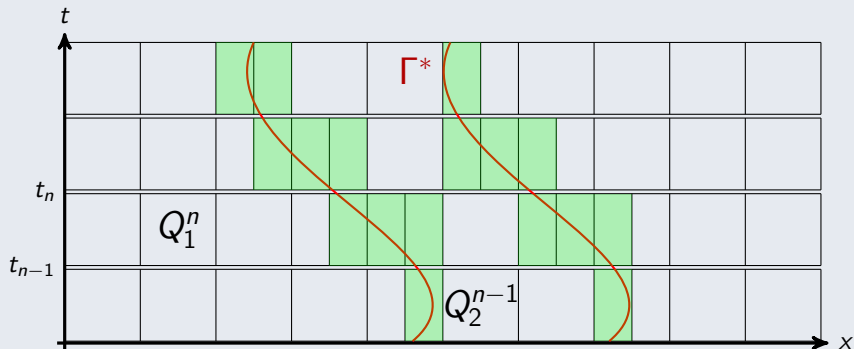
Nitsche-DG-XFEM discretization

Space-time FE

$I_n = (t_{n-1}, t_n]$, $Q^n = \Omega \times I_n$. V_n : standard FE space on Ω .

$W_n := \{v : Q^n \rightarrow \mathbb{R} \mid v(x, t) = \phi_0(x) + t\phi_1(x), \phi_0, \phi_1 \in V_n\}$

$W := \{v : Q \rightarrow \mathbb{R} \mid v|_{Q^n} \in W_n\}$ (space-time FE).



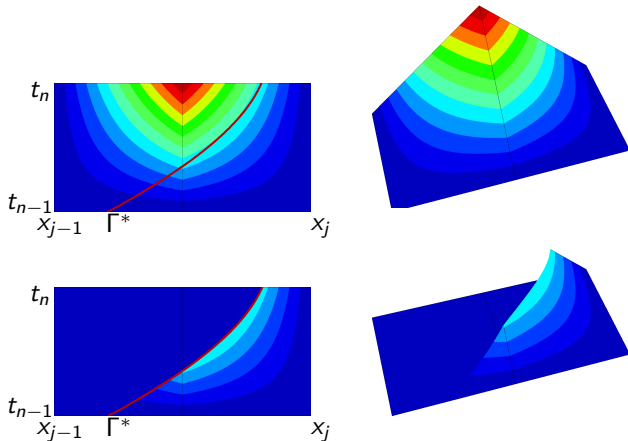


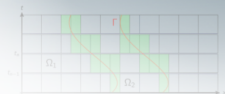
Approximating discontinuities

Space-time FE \Rightarrow Space-time XFEM

$$Q_i^n := \cup_{t \in I_n} \Omega_i(t), \quad R_i^n : \text{restriction to } Q_i^n$$

$$W_n^\Gamma := R_1^n W_n \oplus R_2^n W_n, \quad W^{\Gamma*} := \{v : Q \rightarrow \mathbb{R} \mid v|_{Q^n} \in W_n^\Gamma\}$$

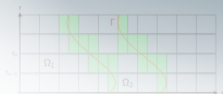




Bilinear forms (within time slab Q^n) I

Conforming part

$$a^n(u, v) = \sum_{i=1}^2 \int_{Q_i^n} \left(\frac{\partial u_i}{\partial t} + \mathbf{w} \cdot \nabla u_i \right) \beta_i v_i + \alpha_i \beta_i \nabla u_i \cdot \nabla v_i \, dx \, dt$$



Bilinear forms (within time slab Q^n) I

Conforming part

$$a^n(u, v) = \sum_{i=1}^2 \int_{Q_i^n} \left(\frac{\partial u_i}{\partial t} + \mathbf{w} \cdot \nabla u_i \right) \beta_i v_i + \alpha_i \beta_i \nabla u_i \cdot \nabla v_i \, dx \, dt$$

Discontinuous Galerkin Upwind w.r.t. time:

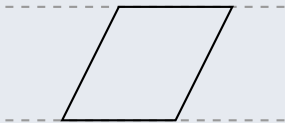
$$d^n(u, v) = \int_{\Omega} \beta(\cdot, t_n) [u]^{n-1} v_+^{n-1} \, dt$$



Bilinear forms (within time slab Q^n) II

Nitsche method for Henry condition:

$$- \int_{Q^n} \beta \operatorname{div}(\alpha \nabla u) v \, dx$$

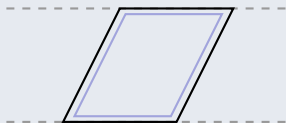




Bilinear forms (within time slab Q^n) II

Nitsche method for Henry condition:

$$-\int_{Q^n} \beta \operatorname{div}(\alpha \nabla u) v \, dx = \int_{Q^n} \alpha \beta \nabla u \nabla v \, dx - \int_{\partial Q^n} \begin{pmatrix} \alpha \nabla u \\ 0 \end{pmatrix} \cdot (\mathbf{n}^*) v \, ds$$

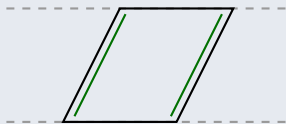




Bilinear forms (within time slab Q^n) II

Nitsche method for Henry condition:

$$\begin{aligned}
 & - \int_{Q^n} \beta \operatorname{div}(\alpha \nabla u) v \, dx = \int_{Q^n} \alpha \beta \nabla u \nabla v \, dx - \int_{\partial Q^n} \begin{pmatrix} \alpha \nabla u \\ 0 \end{pmatrix} \cdot (\mathbf{n}^*) v \, ds \\
 = & \dots - \int_{\Gamma_*^n} \nu \alpha \nabla u \cdot \mathbf{n} \beta v \, ds
 \end{aligned}$$



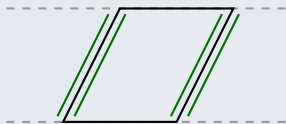
$$\nu = 1 / \sqrt{1 + (\mathbf{w} \cdot \mathbf{n})^2}: \int_{t^{n-1}}^{t^n} \int_{\Gamma^n} f \, ds \, dt = \int_{\Gamma_*^n} \nu f \, ds,$$



Bilinear forms (within time slab Q^n) II

Nitsche method for Henry condition:

$$\begin{aligned}
 & - \int_{Q^n} \beta \operatorname{div}(\alpha \nabla u) v \, dx = \int_{Q^n} \alpha \beta \nabla u \nabla v \, dx - \int_{\partial Q^n} \begin{pmatrix} \alpha \nabla u \\ 0 \end{pmatrix} \cdot (\mathbf{n}^*) v \, ds \\
 & = \dots - \int_{\Gamma_*^n} \nu \alpha \nabla u \cdot \mathbf{n} \beta v \, ds \\
 & \rightarrow \dots - \sum_{i=1}^2 \int_{\Gamma_*^n} \nu \{ \alpha \nabla u \cdot \mathbf{n} \}_{\Gamma_*^n} \beta_i v \, ds \\
 & = \dots - \int_{\Gamma_*^n} \nu \{ \alpha \nabla u \cdot \mathbf{n} \}_{\Gamma_*^n} [\beta v]_{\Gamma_*^n} \, ds \quad \text{A}
 \end{aligned}$$



with $\{\cdot\}_{\Gamma_*^n}$ suitable **volume** weighted average.

$$\nu = 1 / \sqrt{1 + (\mathbf{w} \cdot \mathbf{n})^2}: \int_{t^{n-1}}^{t^n} \int_{\Gamma^n} f \, ds \, dt = \int_{\Gamma_*^n} \nu f \, ds,$$



Bilinear forms (within time slab Q^n) II

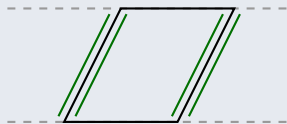
Nitsche method for Henry condition:

$$- \int_{Q^n} \beta \operatorname{div}(\alpha \nabla u) v \, dx = \int_{Q^n} \alpha \beta \nabla u \nabla v \, dx - \int_{\partial Q^n} \begin{pmatrix} \alpha \nabla u \\ 0 \end{pmatrix} \cdot (\mathbf{n}^*) v \, ds$$

$$= \dots - \int_{\Gamma_*^n} \nu \alpha \nabla u \cdot \mathbf{n} \beta v \, ds$$

$$\rightarrow \dots - \sum_{i=1}^2 \int_{\Gamma_*^n} \nu \{ \alpha \nabla u \cdot \mathbf{n} \}_{\Gamma_*^n} \beta_i v \, ds$$

$$= \dots - \int_{\Gamma_*^n} \nu \{ \alpha \nabla u \cdot \mathbf{n} \}_{\Gamma_*^n} [\beta v]_{\Gamma_*^n} \, ds \quad \text{A}$$

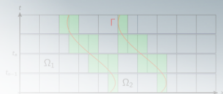


$$\rightarrow - \int_{\Gamma_*^n} \nu \{ \alpha \nabla v \cdot \mathbf{n} \}_{\Gamma_*^n} [\beta u]_{\Gamma_*^n} \, ds \quad \text{B} + \lambda h_n^{-1} \int_{\Gamma_*^n} \nu [\beta u]_{\Gamma_*^n} [\beta v]_{\Gamma_*^n} \, ds, \quad \text{C}$$

with $\{\cdot\}_{\Gamma_*^n}$ suitable **volume** weighted average. $\lambda > 0$: stabilization parameter

and $\nu = 1/\sqrt{1 + (\mathbf{w} \cdot \mathbf{n})^2}$: $\int_{t_{n-1}}^{t_n} \int_{\Gamma^n} f \, ds \, dt = \int_{\Gamma_*^n} \nu f \, ds$,

$$N_{\Gamma_*^n}^n(c, v) := \text{A} + \text{B} + \text{C}$$



Nitsche-DG-XFEM variational problem

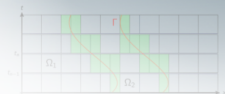
global bilinearforms

$$a(u, v) = \sum_{n=1}^N a^n(u, v), \quad \text{similarly : } d(u, v), N_{\Gamma^*}(u, v).$$

Discrete problem

Determine $U \in W^{\Gamma^*}$ such that

$$\begin{aligned} B(U, V) &= f(V) \quad \text{for all } V \in W^{\Gamma^*}, \\ B(U, V) &:= a(U, V) + d(U, V) + N_{\Gamma^*}(U, V). \end{aligned}$$

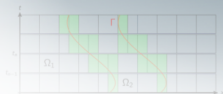


Error analysis (results)

Theorem

Error analysis for linear (space+time) FE

$$\|(u - U)(\cdot, t_N)\|_{L^2(\Omega^N)} \leq c(h^2 + \Delta t^2).$$



Error analysis (results)

Theorem

Error analysis for linear (space+time) FE

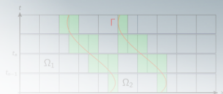
$$\|(u - U)(\cdot, t_N)\|_{L^2(\Omega^N)} \leq c(h^2 + \Delta t^2).$$

Remark:

for standard space-time DG [V. Thomee] (no Nitsche, no XFEM):

$$\|(u - U)(\cdot, t_N)\|_{L^2(\Omega^N)} \leq c(h^2 + \Delta t^3)$$

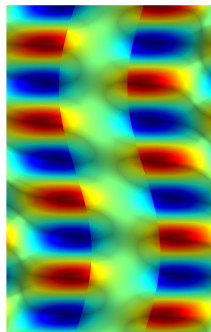
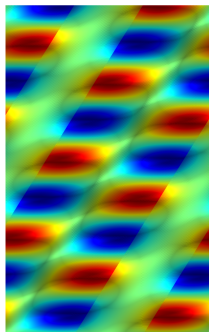
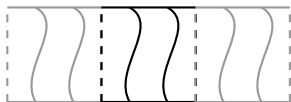
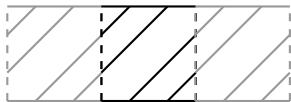
Concept of V. Thomee needs tensor product decomposition of the spaces which we don't have for moving interfaces.



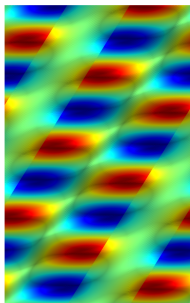
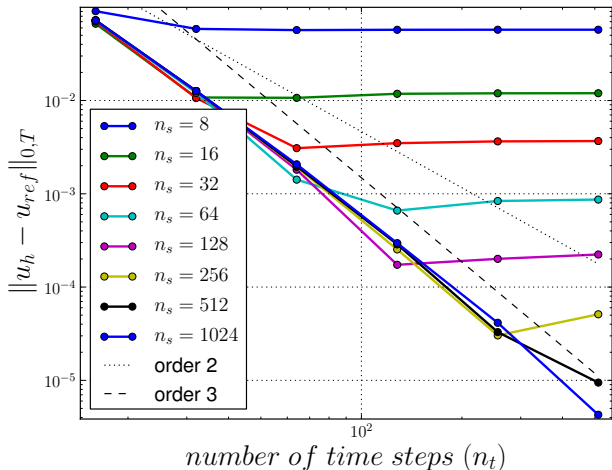
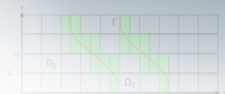
Numerical experiment

Numerical example in (1+1)D

Diffusion dominates, periodic boundary conditions, artificial source terms



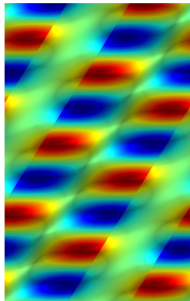
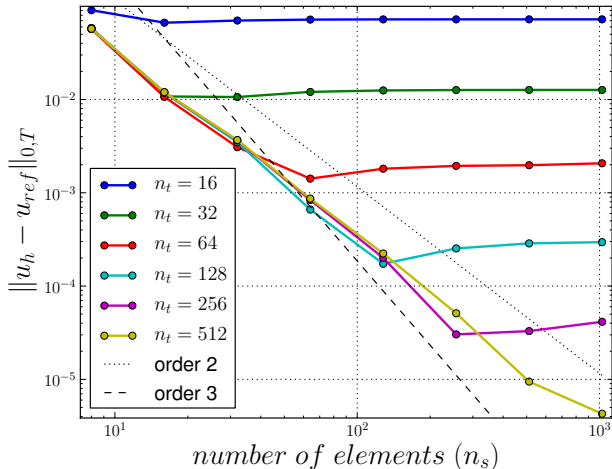
Discretization error (temporal convergence)



This indicates: $\|(U - u)(\cdot, t_N)\|_{L^2(\Omega)} \sim \Delta t^3$ if h sufficiently small.



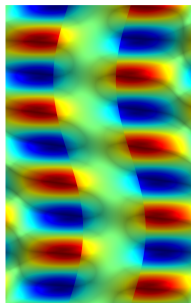
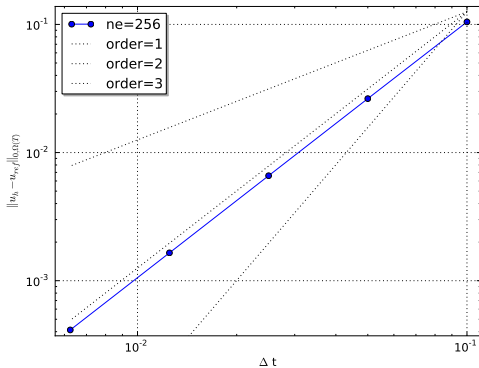
Discretization error (spatial convergence)



This indicates: $\|(U - u)(\cdot, t_N)\|_{L^2(\Omega)} \sim h^2$ if Δt sufficiently small.

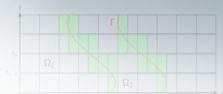


Numerical example (continued): Non-planar interface



This indicates: $\|(U - u)(\cdot, t_N)\|_{L^2(\Omega)} \sim \Delta t^3 \Delta t^2$ if h sufficiently small.

With sufficiently fine quadrature we reobtain $\|(U - u)(\cdot, t_N)\|_{L^2(\Omega)} \sim \Delta t^3$.



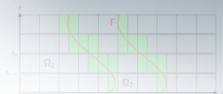
Conclusion

Discretization

- ▶ (Domain-)piecewise continuous approximation + XFEM
- ▶ Nitsche(-XFEM) for interface conditions
- ▶ Space-time FEM with (P1) Discontinuous Galerkin in time.
 [**space-time integrals** \Rightarrow *Composite quadrature in $(n+1) D$*]

Quadrature in $(3+1)D$

- ▶ Quadr. on cutted 4D geometries \Rightarrow **decomposition** rules **into pentatopes**
- ▶ Implementation on the way
- ▶ Limitations (so far?!) to planar space-time interfaces $\Rightarrow \mathcal{O}(\Delta t^2)$



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Thank you for your attention!

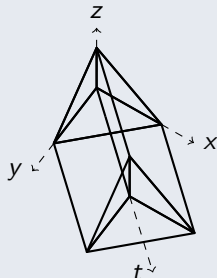


Decomposition into simplices

The reference element can be decomposed into simplices

- (1 + 1) : \hat{Q} is a square \rightarrow 2 triangles
 (2 + 1) : \hat{Q} is a (regular) prism \rightarrow 3 tetrahedra
 (3 + 1) : \hat{Q} is a (regular) prism-4 \rightarrow 4(?) pentatopes(?)

The reference prism-4 \hat{Q}



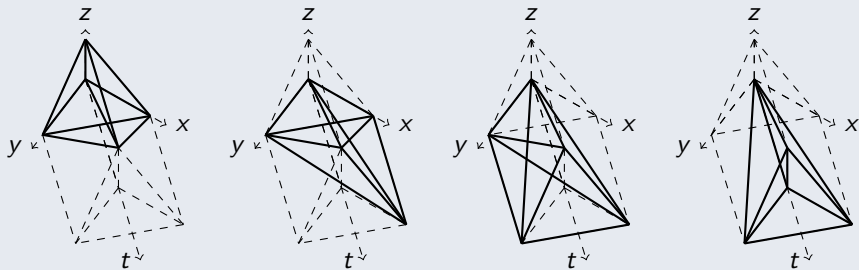


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The reference prism-4 \hat{Q} and it's decomposition



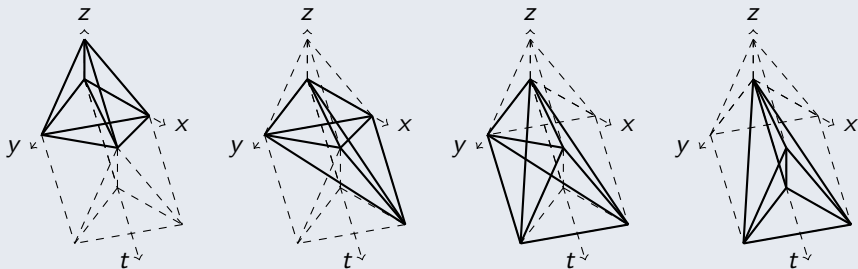


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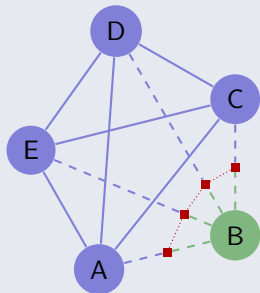


Consider the quadrature problem on (n+1)-simplex!



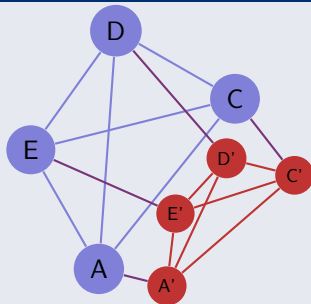
Slicing the pentatope

(Non-degenerated) Case 1:



cutted pentatope

interface

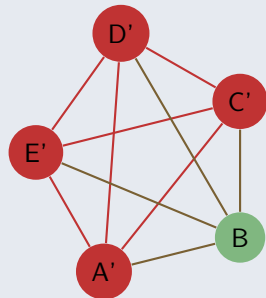


(irregular) prism-4

↓ (decomposition)

4 pentatopes

1 tetrahedra



pentatope

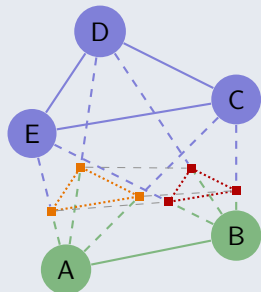
↓

1 pentatope



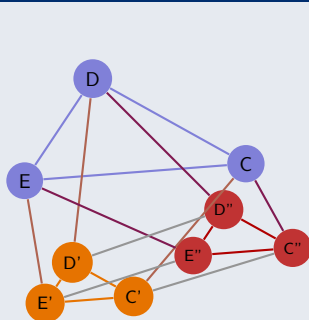
Slicing the pentatope

(Non-degenerated) Case 2:



cutted pentatope

interface



(irregular) hypertriangle
 \downarrow (decomposition)

6 pentatopes

+ (irregular) prism-4

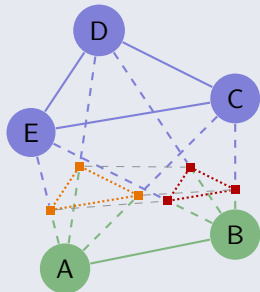
\downarrow
 4 pentatopes

prism-3 \rightarrow 3 tetrahedra



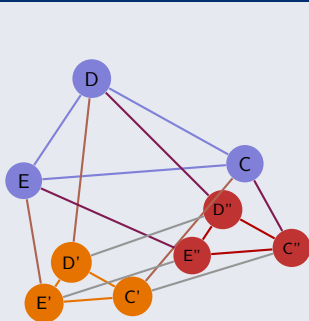
Slicing the pentatope

(Non-degenerated) Case 2:



cutted pentatope

interface



(irregular) hypertriangle

↓ (decomposition)

6 pentatopes

+ (irregular) prism-4

↓

4 pentatopes

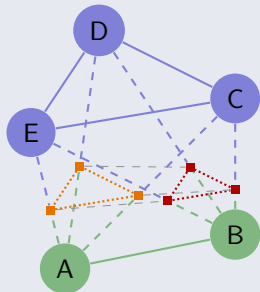
prism-3 → 3 tetrahedra

Step 4: Decomposition into one-phase $(n+1)$ -simplices and n -simplices!



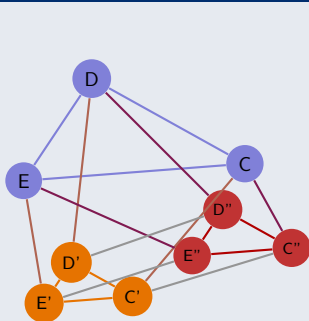
Slicing the pentatope

(Non-degenerated) Case 2:



cutted pentatope

interface



(irregular) hypertriangle

↓ (decomposition)

6 pentatopes

+

(irregular) prism-4

↓

4 pentatopes

prism-3 → 3 tetrahedra

Step 4: Decomposition into one-phase $(n+1)$ -simplices and n -simplices!

Decomposition of the hypertriangle into 6 pentatopes

