

Model Order Reduction Techniques I & II

RB: *A Posteriori* Error Estimation

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Sommersemester 2019

"Truth" Problem Statement

Given $\mu \in \mathcal{D} \subset \mathbb{R}^P$, evaluate

$$(\cdot) = (\cdot)^{\mathcal{N}}$$

$$s(\mu) = f(u(\mu); \mu)$$

where $u(x; \mu) \in X$ satisfies

$$a(u(\mu), v; \mu) = f(v; \mu), \quad \forall v \in X(\Omega).$$

Assumptions:

- ▶ linearity, coercivity, continuity;
- ▶ affine parameter dependence; and
- ▶ compliance: $\ell = f$, a symmetric.

Reduced Basis Sample and Space

Parameter samples:

$$S_N = \{\mu^1 \in \mathcal{D}, \dots, \mu^N \in \mathcal{D}\}, \quad 1 \leq N \leq N_{\max},$$

with

$$S_1 \subset S_2 \subset \dots \subset S_{N_{\max}-1} \subset S_{N_{\max}} \subset \mathcal{D}.$$

Lagrangian reduced basis spaces:

$$W_N = \text{span}\left\{ \underbrace{u(\mu^n)}_{\text{“snapshots”}}, \quad 1 \leq n \leq N \right\}, \quad 1 \leq N \leq N_{\max},$$

with

$$W_1 \subset W_2 \subset \dots \subset W_{N_{\max}-1} \subset W_{N_{\max}} (\subset X).$$

Reduced Basis Approximation

Given $\mu \in \mathcal{D} \subset \mathbb{R}^P$, evaluate

$$s_N(\mu) = f(u_N(\mu); \mu)$$

where $u_N(x; \mu) \in X_N \subset X$ satisfies

$$a(u_N(\mu), v; \mu) = f(v; \mu), \quad \forall v \in X_N.$$

Recall:

- ▶ RB space: $X_N = \text{"Gram-Schmidt"}(W_N)$
- ▶ $u_N(\mu)$ unique (from coercivity, continuity, linear independence)

Coercivity & Continuity

We assume that $a : X \times X \times \mathcal{D} \rightarrow \mathbb{R}$ is

- ▶ coercive

$$(0 <) \alpha(\mu) \equiv \inf_{w \in X} \frac{a(w, w; \mu)}{\|w\|_X^2};$$

- ▶ continuous

$$\gamma(\mu) \equiv \sup_{w \in X} \sup_{v \in X} \frac{a(w, v; \mu)}{\|w\|_X \|v\|_X} (< \infty).$$

Affine Parameter Dependence & Parametric Coercivity

We also assume that $a : X \times X \times \mathcal{D} \rightarrow \mathbb{R}$ is

- ▶ affine

$$a(w, v; \mu) = \sum_{q=1}^{Q_a} \Theta_a^q(\mu) a^q(w, v), \quad \forall w, v \in X$$

- ▶ and parametrically coercive

$$\Theta_a^q(\mu) > 0, \quad \forall \mu \in \mathcal{D}, 1 \leq q \leq Q_a,$$

and

$$a^q(v, v) \geq 0, \quad \forall v \in X, 1 \leq q \leq Q_a.$$

Inner Products and Norms

- ▶ Energy inner product and induced norm (**parameter-dependent**)

$$(((w, v)))_{\mu} = a(w, v; \mu), \quad \forall w, v \in X$$

$$|||w|||_{\mu} = \sqrt{a(w, w; \mu)}, \quad \forall w \in X$$

- ▶ X^e -inner product and induced norm (**parameter-independent**)

$$(w, v)_X \equiv (((w, v)))_{\bar{\mu}} (= a(w, v; \bar{\mu})), \quad \forall w, v \in X$$

$$\|w\|_X \equiv |||w|||_{\bar{\mu}} (= \sqrt{a(w, w; \bar{\mu})}), \quad \forall w \in X$$

Motivation

How do we know that $u_N(\mu)$, $s_N(\mu)$ are accurate? ONLINE

$$\|u(\mu) - u_N(\mu)\|_X \leq \epsilon_{\text{tol},\min}, \quad \forall \mu \in \mathcal{D}$$

$$|s(\mu) - s_N(\mu)| \leq \epsilon_{\text{tol},\min}^s, \quad \forall \mu \in \mathcal{D}$$

How do we know what value of N to take? ONLINE/OFFLINE

N too large \Rightarrow computational inefficiency

N too small \Rightarrow unacceptable uncertainty

How do we choose the sample S_N optimally? OFFLINE

RB space has to approximate manifold \mathcal{M} well, but
RB matrices need to be “well-conditioned.”

Requirements

Our *a posteriori* error bounds, $\Delta_N(\mu)$ and $\Delta_N^s(\mu)$, must be

- ▶ **rigorous** $1 \leq N \leq N_{\max}$

$$\begin{aligned} \|u(\mu) - u_N(\mu)\|_X &\leq \Delta_N(\mu), \quad \forall \mu \in \mathcal{D}, \\ |s(\mu) - s_N(\mu)| &\leq \Delta_N^s(\mu), \quad \forall \mu \in \mathcal{D}. \end{aligned}$$

- ▶ **reasonably sharp**

$$\frac{\Delta_N(\mu)}{\|u(\mu) - u_N(\mu)\|_X} \leq C, \quad \frac{\Delta_N^s(\mu)}{|s(\mu) - s_N(\mu)|} \leq C,$$

where $C \approx 1$.

- ▶ **efficient**

\Rightarrow Online cost depends on N and Q , but not on \mathcal{N} .

Coercivity Lower Bound

We **require** a positive lower bound for the coercivity constant

$$0 < \alpha_{\text{LB}}(\mu) \leq \alpha(\mu), \quad \forall \mu \in \mathcal{D}.$$

This bound can be constructed and calculated explicitly using the

- ▶ “**min** Θ ” Approach
⇒ if a is parametrically coercive,

or (more generally) using the

- ▶ Successive Constraint Method
⇒ also applicable if a is (only) “inf-sup” stable ($\beta_{\text{LB}}(\mu)$).

The “ $\min \Theta$ ” Approach

Lemma

For a parametrically coercive, we have

$$0 < \Theta_a^{\min, \bar{\mu}}(\mu) \leq \alpha(\mu), \quad \forall \mu \in \mathcal{D},$$

where $\Theta_a^{\min, \bar{\mu}} : \mathcal{D} \rightarrow \mathbb{R}_+$ is given by

$$\Theta_a^{\min, \bar{\mu}}(\mu) = \min_{q \in \{1, \dots, Q_a\}} \frac{\Theta_a^q(\mu)}{\Theta_a^q(\bar{\mu})}.$$

Recall X -inner product and norm

$$(w, v)_X \equiv a(w, v; \bar{\mu}), \quad \forall w, v \in X$$

$$\|w\|_X \equiv (w, w)_X^{1/2}, \quad \forall w \in X$$

The “ $\min \Theta$ ” Approach

Similarly, we may develop an upper bound for the continuity constant:

$$\gamma(\mu) < \gamma_{\text{UB}}(\mu) < \infty, \quad \forall \mu \in \mathcal{D}.$$

NOTE: we do not required $\gamma_{\text{UB}}(\mu)$ for our *a posteriori* error estimation, but only for theoretical clarification.

Lemma

For a parametrically coercive and symmetric, we have

$$\gamma(\mu) \leq \Theta_a^{\max, \bar{\mu}}(\mu) < \infty, \quad \forall \mu \in \mathcal{D},$$

where $\Theta_a^{\max, \bar{\mu}} : \mathcal{D} \rightarrow \mathbb{R}_+$ is given by

$$\Theta_a^{\max, \bar{\mu}}(\mu) = \max_{q \in \{1, \dots, Q_a\}} \frac{\Theta_a^q(\mu)}{\Theta_a^q(\bar{\mu})}.$$

The “ $\min \Theta$ ” Approach

If a is **parametrically coercive**, we may choose

- ▶ coercivity constant lower bound

$$\alpha_{\text{LB}}(\mu) \equiv \Theta_a^{\min, \bar{\mu}}(\mu),$$

- ▶ continuity constant upper bound (if a is also **symmetric**)

$$\gamma_{\text{UB}}(\mu) \equiv \Theta_a^{\max, \bar{\mu}}(\mu).$$

Note:

- ▶ Online cost to evaluate $\Theta_a^{\min, \bar{\mu}}(\mu)$: $O(Q_a)$.
- ▶ Choice of inner product important: $(w, v)_X \equiv a(w, v; \bar{\mu})$.
- ▶ Lower bound directly extends to non-symmetric forms b by using the symmetric part

$$b_s(w, v; \mu) = \frac{1}{2}(b(w, v; \mu) + b(v, w; \mu)).$$

Prerequisites – Error Residual Equation

Recall:

- ▶ Truth problem statement: $u(x; \mu) \in X$ satisfies
$$a(u(\mu), v; \mu) = f(v; \mu), \quad \forall v \in X,$$
- ▶ RB problem statement: $u_N(x; \mu) \in X_N \subset X$ satisfies
$$a(u_N(\mu), v; \mu) = f(v; \mu), \quad \forall v \in X_N.$$

Error Residual Equation

The error, $e(\mu) \equiv u(\mu) - u_N(\mu) \in X$, satisfies

$$a(e(\mu), v; \mu) = r_N(v; \mu), \quad \forall v \in X,$$

where the residual is defined as

$$r(v; \mu) \equiv f(v; \mu) - a(u_N(\mu), v; \mu), \quad \forall v \in X.$$

Prerequisites – Dual Norm of Residual

Dual Norm of Residual

Given $\mu \in \mathcal{D}$, the dual norm of $r(v; \mu)$ is defined as

$$\begin{aligned} \|r(\cdot; \mu)\|_{X'} &\equiv \sup_{v \in X} \frac{r(v; \mu)}{\|v\|_X} \\ &= \|\hat{e}(\mu)\|_X, \end{aligned}$$

where $\hat{e}(\mu) \in X$ satisfies

$$(\hat{e}(\mu), v)_X = r(v; \mu), \quad \forall v \in X.$$

It follows that the error residual equation can also be written as

$$a(e(\mu), v; \mu) = (\hat{e}(\mu), v)_X, \quad \forall v \in X.$$

Energy Error Bound

We define

▶ the **error bound**: $\Delta_N^{\text{en}}(\mu) \equiv \frac{\|\hat{e}(\mu)\|_X}{\sqrt{\alpha_{\text{LB}}(\mu)}}$

▶ and the **effectivity**: $\eta_N^{\text{en}}(\mu) \equiv \frac{\Delta_N^{\text{en}}(\mu)}{\|e(\mu)\|_\mu}$

Proposition (Energy Error Bound)

For any $N = 1, \dots, N_{\text{max}}$, the effectivity, $\eta_N^{\text{en}}(\mu)$ satisfies

$$1 \leq \eta_N^{\text{en}}(\mu) \leq \sqrt{\frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}}, \quad \forall \mu \in \mathcal{D}.$$

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▶ the **error bound**:
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Energy Error Bound

Note that effectivity measures quality of error bound

- ▶ Lower bound implies rigor

$$1 \leq \eta_N^{\text{en}}(\mu) \Rightarrow |||e(\mu)|||_{\mu} \leq \Delta_N^{\text{en}}(\mu).$$

- ▶ Upper bound measures sharpness

$$\eta_N^{\text{en}}(\mu) \leq \sqrt{\frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}} \Rightarrow \Delta_N^{\text{en}}(\mu) \leq \sqrt{\frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}} |||e(\mu)|||_{\mu}.$$

For a parametrically coercive and symmetric

$$\theta^{\bar{\mu}}(\mu) \equiv \frac{\Theta_a^{\text{max}, \bar{\mu}}(\mu)}{\Theta_a^{\text{min}, \bar{\mu}}(\mu)} = \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}.$$

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For a parametrically coercive and symmetric

$$\theta^{\bar{\mu}}(\mu) \equiv \frac{\Theta_a^{\text{max}, \bar{\mu}}(\mu)}{\Theta_a^{\text{min}, \bar{\mu}}(\mu)} = \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}.$$

Output Error Bound

We define

▶ the **output error bound**: $\Delta_N^s(\mu) \equiv \frac{\|\hat{e}(\mu)\|_X^2}{\alpha_{\text{LB}}(\mu)}$

▶ and the **output effectivity**: $\eta_N^s(\mu) \equiv \frac{\Delta_N^s(\mu)}{s(\mu) - s_N(\mu)}$

Proposition (Output Error Bound)

For any $N = 1, \dots, N_{\text{max}}$, the effectivity, $\eta_N^s(\mu)$ satisfies

$$1 \leq \eta_N^s(\mu) \leq \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}, \quad \forall \mu \in \mathcal{D}.$$

Output Error Bound

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▶ the **output error bound**: $\Delta_N^s(\mu) \equiv \frac{\|\hat{e}(\mu)\|_X^2}{\alpha_{\text{LB}}(\mu)}$

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Proposition (Output Error Bound)

For any $N = 1, \dots, N_{\text{max}}$, the effectivity, $\eta_N^s(\mu)$ satisfies

$$1 \leq \eta_N^s(\mu) \leq \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}, \quad \forall \mu \in \mathcal{D}.$$

Relative Output Error Bound

We define

- ▶ the **relative output error bound**:

$$\Delta_N^{s,\text{rel}}(\mu) \equiv \frac{\|\hat{e}(\mu)\|_X^2}{\alpha_{\text{LB}}(\mu)s_N(\mu)} = \frac{\Delta_N^s(\mu)}{s_N(\mu)}$$

- ▶ and the **relative output effectivity**:

$$\eta_N^{s,\text{rel}}(\mu) \equiv \frac{\Delta_N^{s,\text{rel}}(\mu)}{(s(\mu) - s_N(\mu))/s(\mu)}$$

Proposition (Relative Output Error Bound)

For any $N = 1, \dots, N_{\max}$ and for $\Delta_N^{s,\text{rel}}(\mu) \leq 1$, the effectivity, $\eta_N^{s,\text{rel}}(\mu)$ satisfies

$$1 \leq \eta_N^{s,\text{rel}}(\mu) \leq 2 \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}, \quad \forall \mu \in \mathcal{D}.$$

Relative Output Error Bound

We define

- ▶ the **relative output error bound**:

$$\Delta_N^{s,\text{rel}}(\mu) \equiv \frac{\|\hat{e}(\mu)\|_X^2}{\alpha_{\text{LB}}(\mu)s_N(\mu)} = \frac{\Delta_N^s(\mu)}{s_N(\mu)}$$

- ▶ and the **relative output effectivity**:

$$\eta_N^{s,\text{rel}}(\mu) \equiv \frac{\Delta_N^{s,\text{rel}}(\mu)}{(s(\mu) - s_N(\mu))/s(\mu)}$$

Proposition (Relative Output Error Bound)

For any $N = 1, \dots, N_{\text{max}}$ and for $\Delta_N^{s,\text{rel}}(\mu) \leq 1$, the effectivity, $\eta_N^{s,\text{rel}}(\mu)$ satisfies

$$1 \leq \eta_N^{s,\text{rel}}(\mu) \leq 2 \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}, \quad \forall \mu \in \mathcal{D}.$$

X -Norm Error Bound

We define

▶ the **error bound**: $\Delta_N(\mu) \equiv \frac{\|\hat{e}(\mu)\|_X}{\alpha_{\text{LB}}(\mu)}$

▶ and the **effectivity**: $\eta_N(\mu) \equiv \frac{\Delta_N(\mu)}{\|e(\mu)\|_X}$

Proposition (X -Norm Error Bound)

For any $N = 1, \dots, N_{\max}$, the effectivity, $\eta_N(\mu)$ satisfies

$$1 \leq \eta_N(\mu) \leq \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}, \quad \forall \mu \in \mathcal{D}.$$

X -Norm Error Bound

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Proposition (X -Norm Error Bound)

For any $N = 1, \dots, N_{\max}$, the effectivity, $\eta_N(\mu)$ satisfies

$$1 \leq \eta_N(\mu) \leq \frac{\gamma_{\text{UB}}(\mu)}{\alpha_{\text{LB}}(\mu)}, \quad \forall \mu \in \mathcal{D}.$$

Error Bounds – Remarks

Remarks:

- ▶ The error bounds are rigorous upper bounds for the reduced basis error for any $N = 1, \dots, N_{\max}$ and for all $\mu \in \mathcal{D}$.
- ▶ The upper bounds for the effectivities are
 - ▶ independent of N , and
 - ▶ independent of \mathcal{N} if $\alpha_{\text{LB}}(\mu)$ only depends on μ ,and are thus stable with respect to RB and FEM refinement.
- ▶ Results for energy norm (and \mathbf{X} -norm) bound directly extend to noncompliant (& nonsymmetric) problems
 - ▶ if we choose an appropriate definition for the energy (and \mathbf{X}) norm

Offline-Online Decomposition

Crucial ingredient: Dual norm of residual $\|\hat{e}(\mu)\|_X$

We expand $u_N(\mu) = \sum_{j=1}^N u_{Nj}(\mu) \zeta^j$

and obtain from the definition of the residual and affine dependence

$$\begin{aligned} r(v; \mu) &= f(v) - a(u_N(\mu), v; \mu) \\ &= f(v) - a\left(\sum_{n=1}^N u_{Nn}(\mu) \zeta_n, v; \mu\right) \\ &= f(v) - \sum_{n=1}^N u_{Nn}(\mu) a(\zeta_n, v; \mu) \\ &= f(v) - \sum_{n=1}^N u_{Nn}(\mu) \sum_{q=1}^{Q_a} \Theta_a^q(\mu) a^q(\zeta_n, v) \end{aligned}$$

For simplicity, we assume here that $f(v)$ does not depend on μ .

Offline-Online Decomposition

Riesz representation:

$$\begin{aligned} (\hat{e}(\mu), v)_X &= r(v; \mu) \\ &= f(v) - \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) a^q(\zeta_n, v), \end{aligned}$$

Linear Superposition:

$$\Rightarrow \hat{e}(\mu) = \mathcal{C} + \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) \mathcal{A}_n^q$$

where

$$\begin{aligned} (\mathcal{C}, v)_X &= f(v), & \forall v \in X; \\ (\mathcal{A}_n^q, v)_X &= -a^q(\zeta_n, v), & \forall v \in X, \\ & & 1 \leq n \leq N, 1 \leq q \leq Q_a. \end{aligned}$$

Offline-Online Decomposition

Riesz representation:

$$\begin{aligned}(\hat{e}(\mu), v)_X &= r(v; \mu) \\ &= f(v) - \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) a^q(\zeta_n, v),\end{aligned}$$

Linear Superposition:

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Offline-Online Decomposition

Thus

$$\begin{aligned}
 & \|\hat{e}(\mu)\|_X^2 \\
 &= \left(\mathbf{c} + \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) \mathcal{A}_n^q, \cdot \right)_X \\
 &= (\mathbf{c}, \mathbf{c})_X + \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) \left\{ \right. \\
 & \quad \left. 2(\mathbf{c}, \mathcal{A}_n^q)_X + \sum_{q'=1}^{Q_a} \sum_{n'=1}^N \Theta_a^{q'}(\mu) u_{Nn'}(\mu) (\mathcal{A}_n^q, \mathcal{A}_{n'}^{q'})_X \right\}
 \end{aligned}$$

Offline-Online Decomposition

Thus

$$\begin{aligned}
 & \|\hat{e}(\mu)\|_X^2 \\
 &= \left(\mathcal{C} + \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) \mathcal{A}_n^q, \cdot \right)_X \\
 &= (\mathcal{C}, \mathcal{C})_X + \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) \left\{ \right. \\
 & \quad \left. 2(\mathcal{C}, \mathcal{A}_n^q)_X + \sum_{q'=1}^{Q_a} \sum_{n'=1}^N \Theta_a^{q'}(\mu) u_{Nn'}(\mu) (\mathcal{A}_n^q, \mathcal{A}_{n'}^{q'})_X \right\}
 \end{aligned}$$

Offline-Online Decomposition

Offline: *once, parameter independent*

- ▶ Compute $\mathcal{C}, \mathcal{A}_n^q$, $1 \leq n \leq N_{\max}$, $1 \leq q \leq Q_a$, from

$$\begin{aligned} (\mathcal{C}, v)_X &= f(v), & \forall v \in X; \\ (\mathcal{A}_n^q, v)_X &= -a^q(\zeta_n, v), & \forall v \in X, \\ & & 1 \leq n \leq N, 1 \leq q \leq Q_a. \end{aligned}$$

- ▶ Form/Store $(\mathcal{C}, \mathcal{C})_X$, $(\mathcal{C}, \mathcal{A}_n^q)_X$, $(\mathcal{A}_n^q, \mathcal{A}_{n'}^{q'})_X$,
 $1 \leq n, n' \leq N_{\max}, 1 \leq q, q' \leq Q_a$.

Complexity depends on N , Q_a , and \mathcal{N} .

Offline-Online Decomposition

Offline: *once, parameter independent*

- ▶ Compute $\mathcal{C}, \mathcal{A}_n^q$, $1 \leq n \leq N_{\max}$, $1 \leq q \leq Q_a$, from

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- ▶ Form/Store $(\mathcal{C}, \mathcal{C})_X$, $(\mathcal{C}, \mathcal{A}_n^q)_X$, $(\mathcal{A}_n^q, \mathcal{A}_{n'}^{q'})_X$,
 $1 \leq n, n' \leq N_{\max}, 1 \leq q, q' \leq Q_a$.

Complexity depends on N , Q_a , and \mathcal{N} .

Offline-Online Decomposition

Online: *many times, for each new μ*
 (and associated solution $u_N(\mu)$)

- Evaluate

$$\begin{aligned} & \|\hat{e}(\mu)\|_X^2 \\ &= (\mathcal{C}, \mathcal{C})_X + \sum_{q=1}^{Q_a} \sum_{n=1}^N \Theta_a^q(\mu) u_{Nn}(\mu) \left\{ \right. \\ & \quad \left. 2(\mathcal{C}, \mathcal{A}_n^q)_X + \sum_{q'=1}^{Q_a} \sum_{n'=1}^N \Theta_a^{q'}(\mu) u_{Nn'}(\mu) (\mathcal{A}_n^q, \mathcal{A}_{n'}^{q'})_X \right\} \\ & \quad - O(Q_a^2 N^2) \end{aligned}$$

Complexity depends on N , Q_a , **but not** \mathcal{N} .

Offline-Online Decomposition

Summary of computational cost:

OFFLINE —

$$\begin{array}{l} O(Q_a N_{\max} \mathcal{N}^\bullet) \quad + \quad O(Q_a^2 N_{\max}^2 \mathcal{N}) \\ \text{solve Poisson problems} \quad \quad \quad \text{form } \mu\text{-independent inner products} \end{array} ;$$

ONLINE —

$$\begin{array}{l} O(Q_a^2 N^2) \\ \text{evaluate } \|\hat{e}(\mu)\|_{X\text{-sum}} \end{array} ;$$

Online cost is **independent** of \mathcal{N} .

Algebraic Equations

Offline: *once, parameter independent*

- ▶ Compute $\underline{\mathbf{C}} \in \mathbb{R}^{\mathcal{N}}$ and $\underline{\mathbf{A}}^q \in \mathbb{R}^{\mathcal{N} \times \mathcal{N}}$, $1 \leq q \leq Q_a$, from

$$\begin{aligned} \underline{\mathbb{X}}^{\mathcal{N}} \underline{\mathbf{C}} &= \underline{\mathbf{F}}^{\mathcal{N}}; \\ \underline{\mathbb{X}}^{\mathcal{N}} \underline{\mathbf{A}}^q &= -\underline{\mathbb{A}}^{\mathcal{N}q} \underline{\mathbb{Z}}_N, \quad 1 \leq q \leq Q_a. \end{aligned}$$

- ▶ Form/Store

$$\begin{aligned} \underline{\mathbf{C}}^T \underline{\mathbb{X}}^{\mathcal{N}} \underline{\mathbf{C}} &\in \mathbb{R}; \\ (\underline{\mathbf{A}}^q)^T \underline{\mathbb{X}}^{\mathcal{N}} \underline{\mathbf{C}} &\in \mathbb{R}^N, \quad 1 \leq q \leq Q_a; \\ (\underline{\mathbf{A}}^{q'})^T \underline{\mathbb{X}}^{\mathcal{N}} \underline{\mathbf{A}}^q &\in \mathbb{R}^{N \times N}, \quad 1 \leq q, q' \leq Q_a. \end{aligned}$$

Algebraic Equations

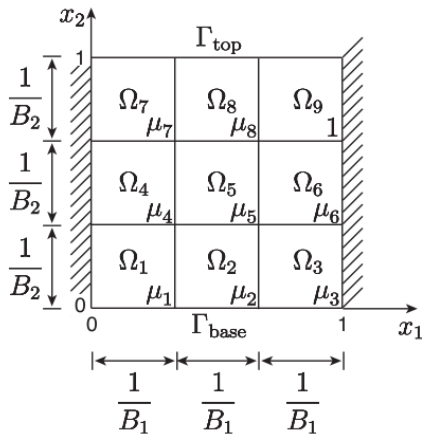
Online: *many times, for each new μ*

(and associated solution $\underline{u}_N(\mu) \in \mathbb{R}^N$)

► Evaluate

$$\begin{aligned} & \|\hat{e}(\mu)\|_{\underline{X}}^2 \\ &= \underline{c}^T \underline{X} \underline{N} \underline{c} + \sum_{q=1}^{Q_a} \Theta_a^q(\mu) (\underline{u}_N(\mu))^T \left\{ \right. \\ & \quad \left. 2(\underline{A}^q)^T \underline{X} \underline{N} \underline{c} + \sum_{q'=1}^{Q_a} \Theta_a^{q'}(\mu) (\underline{A}^{q'})^T \underline{X} \underline{N} \underline{A}^q \underline{u}_N(\mu) \right\} \\ & \quad - O(Q_a^2 N^2) \end{aligned}$$

Example: ThermalBlock



$$\bar{\Omega} = \cup_{i=1}^{B_1 B_2} \bar{\Omega}_i$$

Example: ThermalBlock

Problem Statement

Given $\mu = (\mu_1, \dots, \mu_P) \subset \mathcal{D} \equiv [\mu^{\min}, \mu^{\max}]^P$, evaluate

$$s(\mu) = f(u(\mu)) \qquad \ell = f$$

where $u(\mu) \in X$ satisfies

$$a(u(\mu), v; \mu) = f(v), \quad \forall v \in X.$$

Here, $P = B_1 B_2 - 1$, and we assume that

$\mu^{\min} = 1/\sqrt{\mu_r}$, $\mu^{\max} = \sqrt{\mu_r}$, for $1 < \mu_r < \infty$,
such that $\mu^{\max}/\mu^{\min} = \mu_r$.

Example: ThermalBlock

Here, $\forall v \in X$,

$$f(v) \equiv \int_{\Gamma_{\text{base}}} v,$$

compliant $\ell = f$

and, $\forall w, v \in X$,

$$a(w, v; \mu) = \sum_{i=1}^P \mu_i \int_{\Omega_i} \nabla w \cdot \nabla v + \int_{\Omega_{P+1}} \nabla w \cdot \nabla v,$$

where $\bar{\Omega} = \cup_{i=1}^{P+1} \bar{\Omega}_i$.

Example: ThermalBlock

Inner product, $w, v \in X$,

$$(w, v)_X = \sum_{i=1}^P \bar{\mu}_i \int_{\Omega_i} \nabla w \cdot \nabla v + \int_{\Omega_{P+1}} \nabla w \cdot \nabla v,$$

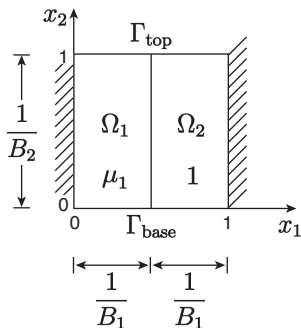
where $\bar{\mu}_i$ is the **reference parameter**.

The bilinear form a is

- ▶ **symmetric**,
- ▶ **(parametrically) coercive**,
 $0 < \frac{1}{\sqrt{\mu_r}} \leq \text{Min}(\mu_1/\bar{\mu}_1, \dots, \mu_P/\bar{\mu}_P, 1) \leq \alpha^e(\mu)$,
- ▶ and **continuous**,
 $\gamma^e(\mu) < \text{Max}(\mu_1/\bar{\mu}_1, \dots, \mu_P/\bar{\mu}_P, 1) \leq \sqrt{\mu_r} < \infty$.

The linear form f is **bounded**.

Example: ThermalBlock $P = 1$



We assume

$$1/\mu_1^{\min} = \mu_1^{\max} = \sqrt{\mu_r} = 10,$$

and choose $\mathcal{N} = 256$.

We set $\bar{\mu} = 1$ and have

$$\Theta_a^1(\mu) = \mu_1, \quad \Theta_a^2(\mu) = 1.$$

Thus,

$$\Theta_a^{\min, \bar{\mu}}(\mu_1) = \text{Min}(\mu_1, 1),$$

$$\Theta_a^{\max, \bar{\mu}}(\mu_1) = \text{Max}(\mu_1, 1),$$

and therefore

$$\theta^{\bar{\mu}}(\mu_1) = \text{Max}\left(\frac{1}{\mu_1}, \mu_1\right),$$

and

$$\theta^{\bar{\mu}}(\mu_1) \leq \sqrt{\mu_r}, \quad \forall \mu_1 \in \mathcal{D}.$$

Example: ThermalBlock $P = 1$

Output error bound and effectivities

N	$\Delta_{N,\max}^s$	$\eta_{N,\text{ave}}^s$	$\eta_{N,\max}^s$
1	7.2084 E+00	2.3417	3.3305
2	4.5371 E-01	2.4858	3.6850
3	6.9652 E-04	6.2195	9.8551
4	1.3744 E-07	3.3219	7.2632
5	3.1140 E-11	6.0789	7.0453

[RHP2008]

Note that: $\eta_{N,\max}^s(\mu_1) \leq \eta_{\max,\text{UB}}^s \equiv \sqrt{\mu_r} = 10$.

Here

- ▶ Maximum output error bound: $\Delta_{N,\max}^s = \max_{\mu \in \Xi_{\text{train}}} \Delta_N^s(\mu)$
- ▶ Average output effectivity: $\eta_{N,\text{ave}}^s = \frac{1}{|\Xi_{\text{train}}|} \sum_{\mu \in \Xi_{\text{train}}} \eta_N^s(\mu)$
- ▶ Maximum output effectivity: $\eta_{N,\max}^s = \max_{\mu \in \Xi_{\text{train}}} \eta_N^s(\mu)$

Example: ThermalBlock $P = 8$

We assume $B_1 = B_2 = 3$, $\mathcal{N} = 661$

$$1/\mu_i^{\min} = \mu_i^{\max} = \sqrt{\mu_r} = 10, \quad 1 \leq i \leq 8,$$

and set $\bar{\mu}_i = 1$, $1 \leq i \leq 8$.

We have

$$\Theta_a^i(\mu) = \mu_i, \quad 1 \leq i \leq 8; \text{ and } \Theta_a^9(\mu) = 1.$$

Thus,

$$\Theta_a^{\min, \bar{\mu}}(\mu) = \text{Min}(1, \mu_1, \dots, \mu_8),$$

$$\Theta_a^{\max, \bar{\mu}}(\mu) = \text{Max}(1, \mu_1, \dots, \mu_8),$$

and therefore

$$\theta^{\bar{\mu}}(\mu_1) = \text{Max}\left[1, \frac{1}{\mu_1}, \dots, \frac{1}{\mu_8}\right] \times \text{Max}[1, \mu_1, \dots, \mu_8],$$

and

$$\theta^{\bar{\mu}}(\mu_1) \leq \mu_r, \quad \forall \mu \in \mathcal{D}.$$

Example: ThermalBlock $P = 8$

Output error bound and effectivities

N	$\Delta_{N,\max}^s$	$\eta_{N,\text{ave}}^s$	$\eta_{N,\max}^s$
10	2.2036 E+00	6.7067	31.2850
20	2.0020 E-01	7.5587	37.3024
30	1.5100 E-02	12.1138	62.2537
40	1.2000 E-03	14.4598	73.1151
50	1.0000 E-04	10.2566	57.5113
60	1.0000 E-05	8.0103	43.3108
70	2.0000 E-06	8.4598	36.5435

[RHP2008]

Note that: $\eta_{N,\max}^s(\mu_1) \leq \eta_{\max,\text{UB}}^s \equiv \mu_r = 100.$